Let  $S = \{v_1, v_2, ..., v_n\}$  be a basis for an inner product space V. Then S is an orthonormal basis for V if

a)( $\mathbf{v}_i, \mathbf{v}_j$ )=0 for  $i \neq j$ b)( $\mathbf{v}_i, \mathbf{v}_i$ )=1 for all i

Let  $\mathbf{S} = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  be an orthonormal basis for an inner product space V and let v be any vector in V.

Then 
$$\boldsymbol{v} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \dots + c_n \mathbf{v}_n$$

where  $c_i = (\mathbf{v}, \mathbf{v}_i)$  for all *i* 

# $(\mathbf{v}, \mathbf{v}_{1}) = (c_{1}\mathbf{v}_{1} + c_{2}\mathbf{v}_{2} + \dots + c_{i}\mathbf{v}_{i} + \dots + c_{n}\mathbf{v}_{n}, \mathbf{v}_{i})$ $= (c_{1}\mathbf{v}_{1}, \mathbf{v}_{i}) + (c_{2}\mathbf{v}_{2}, \mathbf{v}_{i}) + \dots + (c_{i}\mathbf{v}_{i}, \mathbf{v}_{i}) + \dots + (c_{n}\mathbf{v}_{n}, \mathbf{v}_{i}))$ $= c_{1}(\mathbf{v}_{1}, \mathbf{v}_{i}) + c_{2}(\mathbf{v}_{2}, \mathbf{v}_{i}) + \dots + c_{i}(\mathbf{v}_{i}, \mathbf{v}_{i}) + \dots + c_{n}(\mathbf{v}_{n}, \mathbf{v}_{i}))$ $= c_{1} \cdot 0 + c_{2} \cdot 0 + \dots + c_{i} \cdot 1 + \dots + c_{n} \cdot 0$

 $= c_i$ 

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If  $S = \{u_1, u_2, ..., u_n\}$  is a basis (not orthonormal) for an inner product space V, is there a way to convert it to an orthonormal basis?

• Replace the basis  $\mathbf{S} = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3\} = \left\{ \begin{bmatrix} 1\\0\\1 \end{bmatrix}, \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 2\\1\\0 \end{bmatrix} \right\}$ with an orthonormal basis  $\{\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3\}$  $\mathbf{v}_1 = \mathbf{u}_1 \Rightarrow \mathbf{w}_1 = \frac{\mathbf{v}_1}{||\mathbf{v}_1||} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}$  $\mathbf{v}_{2} = \mathbf{u}_{2} - (\mathbf{w}_{1}, \mathbf{u}_{2})\mathbf{w}_{1} = \begin{bmatrix} 1\\0\\0 \end{bmatrix} - \frac{1}{\sqrt{2}} \begin{bmatrix} \frac{1}{\sqrt{2}}\\0\\\frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} \frac{1}{2}\\0\\\frac{1}{\sqrt{2}} \end{bmatrix}$ 

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$$\mathbf{w}_2 = \frac{\mathbf{v}_2}{||\mathbf{v}_2||} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

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$$\mathbf{v}_{3} = \mathbf{u}_{3} - (\mathbf{u}_{3}, \mathbf{w}_{1})\mathbf{w}_{1} - (\mathbf{u}_{3}, \mathbf{w}_{2})\mathbf{w}_{2}$$
$$= \begin{bmatrix} 2\\1\\0\\0\\\frac{1}{\sqrt{2}} \end{bmatrix} - \sqrt{2} \begin{bmatrix} \frac{1}{\sqrt{2}}\\0\\\frac{1}{\sqrt{2}} \end{bmatrix} - \sqrt{2} \begin{bmatrix} \frac{1}{\sqrt{2}}\\0\\-\frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} 0\\1\\0 \end{bmatrix}$$

$$\mathbf{w}_3 = \frac{\mathbf{v}_3}{||\mathbf{v}_3||} = \begin{bmatrix} 0\\1\\0 \end{bmatrix}$$

### Orthonormal set is

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# Comments

- Key idea in Gram-Schmidt is to subtract from every new vector, u<sub>k</sub>, its components in the directions already determined, {v<sub>1</sub>, v<sub>2</sub>,..., v<sub>k-1</sub>}
- When doing Gram-Schmidt by hand, it simplifies the calculation to multiply the newly computed  $\mathbf{v}_k$  by an appropriate scalar to clear fractions in its components. The resulting vectors are normalized at the end of the computation

# **QR** Factorization

In the Gram-Schmidt example, the basis  $\left\{ \begin{bmatrix} 1\\0\\1 \end{bmatrix}, \begin{bmatrix} 1\\0\\0 \end{bmatrix}, \begin{bmatrix} 2\\1\\0 \end{bmatrix} \right\}$  is transformed to



This is called the QR-Factorization of A

# **QR** Factorization

Interpreting these vectors as column vectors of matrices, the following result holds

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 2 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} & 0 \end{bmatrix} \begin{bmatrix} \sqrt{2} & \frac{1}{\sqrt{2}} & \sqrt{2} \\ 0 & \frac{1}{\sqrt{2}} & \sqrt{2} \\ 0 & 0 & 1 \end{bmatrix} = \mathbf{Q}\mathbf{R}$$

This is called the QR-Factorization of  ${\bf A}$ 

# Comments

• Computer programs that compute the QR Factorization use an algorithm that is different from that of the proof, which is essentially Gram-Schmidt.

# Comments

 MATLAB's implementation of QR-Factorization of an mxn matrix A returns an mxm matrix Q with orthonormal columns and an mxn matrix R of the form ⇒ r\*\*\*

The first n columns of  $\mathbf{Q}$ form a basis for the column space of  $\mathbf{A}$ and  $\mathbf{A} = \mathbf{Q}\mathbf{R}$   $= \begin{bmatrix} * & * & * & * \\ \mathbf{0} & * & * & * \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & * \\ 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \end{bmatrix}$ 

## Definitions

- A *square* matrix **Q** that has orthonormal columns is called an <u>orthogonal matrix</u>
- Because of the orthonormal columns,  $\mathbf{Q}^{T}\mathbf{Q} = \mathbf{I}$ . Therefore  $\mathbf{Q}^{-1} = \mathbf{Q}^{T}$